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ABSTRACT.

This paper present different methods for optimal placement of phasor measuring unit (PMU) in power system for complete observability of the system. For smooth and efficient working of the system installation of phasor measuring unit become necessity. But due to high cost of PMU, it is not feasible to place it on every bus system. So, optimization becomes the crucial need. In present work for optimization power system toolbox (PSAT) is used. The proposed methods have been used and verified on IEEE-6, IEEE-9 bus system.

KEYWORDS: phasor measuring unit (PMU), PSAT, observability.

1. INTRODUCTION

In recent years demand of electricity increasing because of advancement of technology and improvement in living standard of people. Power system works at their full capacity which needs close monitoring of system to avoid outages and faults. To make system more reliable and advanced new monitoring systems are being implemented in the system like wide area measurement system where PMU is the key monitoring system. In earlier time traditional monitoring system like SCADA (supervisory control and data acquisition) system is used. But it has many limitations like slow duty cycle and observe system only in steady state.

New technology phasor measuring unit (PMU) is developed in recent years. Its GPS based device which provide time stamped phasor data. Real time-based monitoring can ensure more stable and reliable operation of the system. Data obtained from the PMU is used for complete analysis of the system by using different software at the control centre. PMUs are placed at the buses of the system to measure voltage, current and phase angle. Major constraint in PMU implementation is its cost. Due to very high cost, it's not feasible to place PMU at each bus because of economic and design reason. Therefor optimal placement of PMUs is needed to make system complete observable

1.2 PHASOR MEASURING UNIT (PMU)

Phasor measuring unit(pmu) is synchronized device. It is combination of hardware and software used for measuring phasor angle, voltage and current. PMU provide time stamped data. Time synchronization is done by GPS. Resulting measurement provided by PMU is known as 'synchrophasor'. some applications of PMU as following:

1. Wide area monitoring/measuring system: key system for implementation of smart grid, real time information,
2. Protection: prevention of outages & blackouts
3. State estimation of system
4. Automated control of system

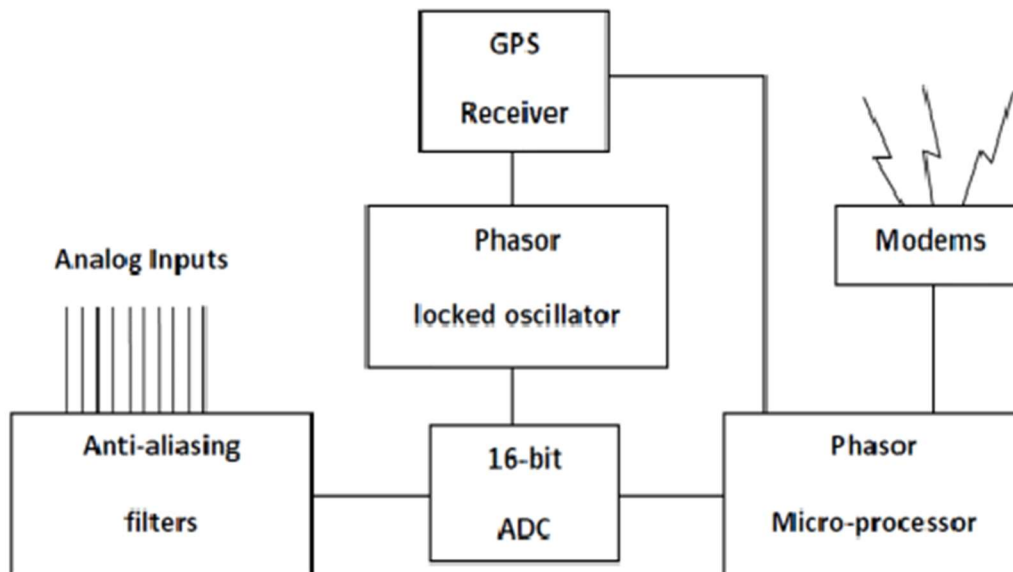


Figure 1. internal structure of pmu

Analog inputs from CT/PT fed to anti-aliasing filters. Filters is used to attenuate frequency above the standard limit of analog to digital converter. Then analog data fed to ADC which convert it to digital form and GPS provide time synchronization. Then timestamped data fed to micro-processor. Sampled data send to modem. Which is utilized at controlled centre using different software's. PMU provide 50-60 samples per cycle.

1.3 RULES FOR PMU PLACEMNET

The following PMU placement rules were proposed in [Baldwin et al.1993]

1. Firstly, assign one voltage measurement to bus where PMU has been placed and one current measurement to each connected branch to the bus.
2. Next assign one voltage pseudo measurement to each node reached by another node which equipped with PMU.
3. Then assign one current pseudo measurement to each branch which connects two buses where voltages are known.
4. Last assign one current pseudo measurement to each branch where current can be directly measured by KCL. It applies when current balance at node is known.

2. CASE STUDY

Simulation of phasor measuring unit placement have been carried out for IEEE 6 and IEEE 9 bus system using PSAT (power system analysis tool box). In this software depth first search, simulated annealing method, graphic theoretic procedure, (N-1) spanning tree method is used for optimal placement.

2.1 IEEE-6 BUS SYSTEM

This model consists of 6 buses,11 connecting lines,3generators ,3 loads,3 supplies,3 demands.

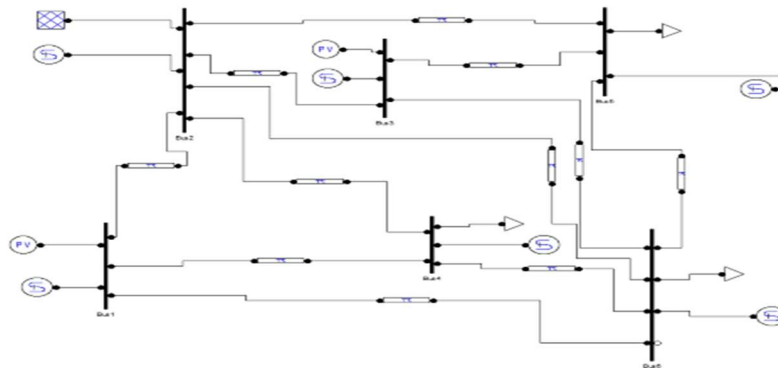


Figure 2. IEEE-6 BUS model

Table 1: Comparison of different method used for optimal placement of PMU for IEEE-6 bus system

Software used	Method	Elapsed time	No. of PMU	Bus no.
PSAT	Depth first search	0h 0m 0.0225s	1	6
	Graph theoretic procedure	0h 0m 0.021447s	1	6
	Annealing method	0h 0m 0.07843s	1	6
	Minimum (N-1) spanning tree	0h 0m 0.03743s	3	2,4,6

2.2 IEEE-9 BUS SYSTEM

This model consists of 9 buses,6 connecting lines,3 transformers, 3 generators and 3 loads.

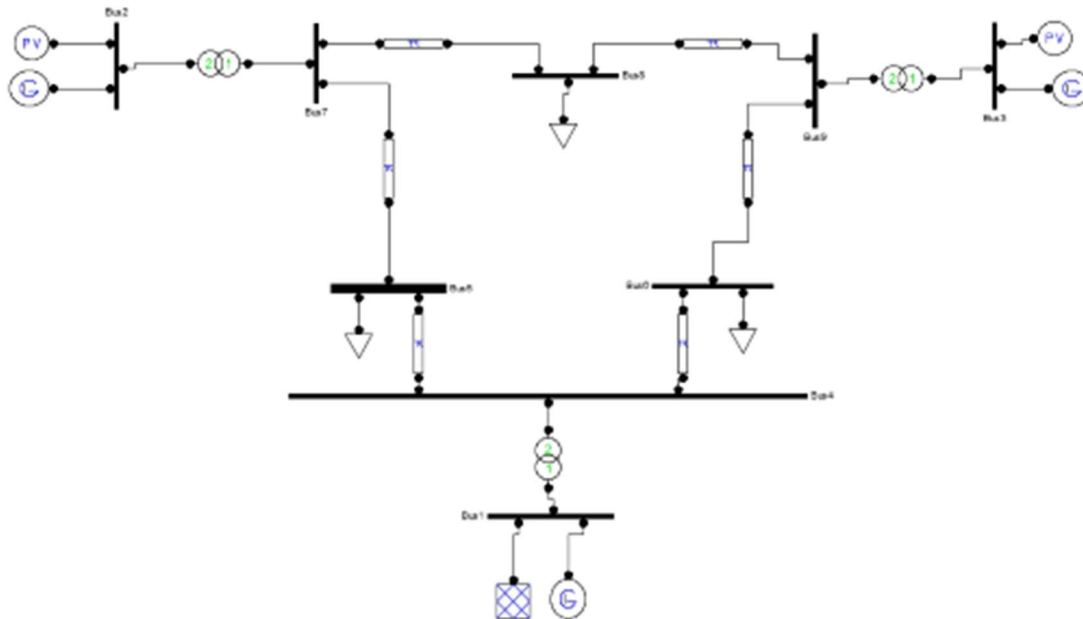


Figure 3. IEEE-9 BUS model

Table 2: comparison of different methods used for optimal placement of PMU for IEEE-9 bus system

Software used	Methods	Elapsed time	No. of PMU	Bus no.
PSAT	Depth first search	0h 0m 0.02607s	3	4,7,9
	Graph theoretic procedure	0h 0m 0.020473s	3	4,7,9
	Annealing method	0h 0m 0.03869s	2	2,1
	Minimum (N-1) spanning tree	0h 0m 0.03658s	3	4,7,9

3. CONCLUSIONS

Phasor measuring unit is new technology that has potential to improve grid operations and conduct real time analysis. The optimal PMU placement decreases the no. of PMUs to be placed and make system fully observable with minimum no. of PMUs.

A methodology and software used to determine minimum no. of PMUs is presented in this paper. As per result comparison annealing method give minimum no. of PMUs but has slow speed. Graph theoretic procedure gives good speed and optimal no. of PMUs. So, it can be considered best amongst the all-other methods.

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